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# **Experimental Investigation of EDM Process Parameters on Aluminum Nano composite using Taguchi Technique**

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### **Abstract**

In recent material removal process, Conventional machining like drilling, milling, grinding etc can be replaced by Non traditional machining because of high surface finish, Minimum tool wear and excellent dimensional accuracy. Particularly for machining high hardened materials like ceramic, composites and super alloys Electrical discharge Machining (EDM) process is preferred. In this paper an attempt is made to machining of Aluminium nano composites. It is fabricated by melting Aluminium alloy 6061 in a crucible and stirred the preheating Multiwall carbon nanotubes (MWCNT) with different Wt% using stir casting technique. Now 16 Experiments with varying three input parameters Current, Pulse On and Pulse Off having four level of factors were conducted. The output parameters can be measured by Surface Roughness value (SR), Material Removal rate (MRR) and Tool wear rate (TWR). From the Taguchi analysis, it is determined that MRR, TWR and SR gives good results when using copper electrode for machining of aluminum nano composite.

## Keywords: Aluminum Nano composites, EDM, MWCNT, and Taguchi design.

### 1. Introduction

The history of **EDM** Machining Techniques goes as far back as the 1770s when it was discovered by an English Scientist. However, Electrical Discharge Machining was not fully taken advantage of until 1943 when Russian scientists learned how the erosive effects of the technique could be controlled and used for machining purposes. When it was originally observed by Joseph Priestly in 1770, EDM Machining was very imprecise and riddled with failures. Commercially developed in the mid 1970s, wire EDM began to be a viable technique that helped shape the metal working industry we see today. In the mid 1980s. The EDM techniques were transferred to a machine tool. This migration made EDM more widely available and appealing over traditional machining processes. The new concept of manufacturing uses non-conventional

sound, light, mechanical, energy sources like chemical, electrical, electrons and ions. With the industrial and technological growth, development of harder and difficult to machine materials, which find wide application in aerospace, nuclear engineering and other industries owing to their high strength to weight ratio, hardness and heat resistance qualities has been witnessed. New developments in the field of material science have led to new engineering metallic materials, composite materials and high tech ceramics having good mechanical properties and thermal characteristics as well as sufficient electrical conductivity so that they can readily be machined by spark erosion. Non-traditional machining has grown out of the need to machine these exotic The machining processes are nontraditional in the sense that they do not employ traditional tools for metal removal and instead they

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directly use other forms of energy. The problems of high complexity in shape, size and higher demand for product accuracy and surface finish can be solved through non-traditional methods. Currently, non-traditional processes possess virtually unlimited capabilities except volumetric material removal rates, for which great advances have been made in the past few years to increase the material removal rates. As removal rate increases, the cost effectiveness of operations also increases, stimulating ever greater uses of non-traditional process. The Electrical Discharge Machining process is employed widely for making tools, dies and other precision parts.

EDM has been replacing drilling, milling, grinding and other traditional machining operations and is now a well-established machining option in many manufacturing industries throughout the world. And is capable of machining geometrically complex or hard material components, that are precise and difficult-to-machine such as heat treated tool steels, composites, super alloys, ceramics, carbides, heat resistant steels etc. being widely used in die and mold making industries, aerospace, aeronautics and nuclear industries. Electric Discharge Machining has also made its presence felt in the new fields such as sports, surgical, medical and instruments, optical, including automotive R&D areas.

## 1.1 Introduction of EDM

Before Electro Discharge Machining (EDM) is an electro-thermal non-traditional machining Process, where electrical energy is used to generate electrical spark and material removal mainly occurs due to thermal energy of the spark. EDM is mainly used to machine difficult-to-machine materials and high strength temperature resistant alloys. EDM can be used to machine difficult geometries in small batches or even on job-shop basis. Work material to be machined by EDM has to be electrically conductive

## 1.2 Principle of EDM

In this process the metal is removing from the work piece due to erosion case by rapidly recurring spark discharge taking place between the tool and work piece. Show the mechanical set up and electrical set up and electrical circuit for electro discharge machining.

### 2. Literature Review

Any project work could not be carried out without previous relevant efforts done. In our case we also have gone through many books, journals, reports, projects and paper presentation which helped us to proceed smoothly and in very sequential manner with lots of knowledge. Here is some literature mentioned to show our gratitude for their help. Dhar and Purohit [1] evaluates the effect of current (c), pulse-on time (p) and air gap voltage (v) on MRR, TWR, ROC of EDM with Al-4Cu-6Si alloy-10 wt. % SiCP composites. This experiment can be using the PS LEADER ZNC EDM machine and a cylindrical brass electrode of 30 mm diameter. And three factors, three levels full factorial design was using and analyzing the results. A second order, non-linear mathematical model has been developed for establishing the relationship among machining parameters. The significant of the models were checked using technique ANOVA and finding the MRR, TWR and ROC increase significant in a non-linear fashion with increase in current karthikeyan et .al [2] has presented the mathematical molding of EDM with aluminium-silicon carbide particulate composites. Mathematical equation is Y=f(V, I, T). And the effect of MRR, TWR, SR with Process parameters taken in to consideration were the current (I), the pulse duration (T) and the percent volume fraction of SiC (25  $\mu$  size). A three-level full factorial design was choosing. Finally, the significant of the models were checked using the ANOVA. The MRR was found to decrease with an increase in the percent volume of SiC, whereas the TWR and the surface roughness increase with an increase in the volume of Sic.[3–7] Evolution the of effect of the EDM Current, electrode marital polarity, pulse duration and rotation of electrode on metal removal rate, TWR, and SR, and the EDM of Al-Sic with 20-25 vol. % SiC, Polarity of the electrode and volume present of SiC, the MRR increased with increased in discharge current and specific current it decreased with increasing in pulse duration. Increasing the speed of the rotation electrode resulted in a positive effect with MRR, TWR and better SR than stationary. The electric motor can be used to rotate the electrode (tool) AV belt as used to transmit he power from the motor to the electrode Optimization parameters for EDM drilling were also developed to summarize the effect of machining characteristic such as MRR, TWR and SR.[8–14].

## 3. Experimental works

In this chapter we are going to discuss about the experimental work which is consist about formation of the L-16 orthogonal array based on Taguchi design, orthogonal array is reduces the total on of experiment, in this experiment total 16 run. And Experimental set up, selection of work piece, tool design, and taking all the value and calculation of MRR (Material Removal Rate), SR (surface Roughness) and TWR (Tool Wear Rate). For this experiment the whole work can be down by Electric Discharge Machine, (die-sinking type) with servo-head (constant gap) and positive polarity for electrode was used to conduct the experiments. Commercial grade EDM oil (specific gravity= 0.78, freezing point= 92°C) was used as dielectric fluid. With internal flushing of cu tool with a pressure of 0.230 kgf/cm<sup>2</sup>. Experiments were conducted with positive polarity of copper electrode. The pulsed discharge current was applied in various steps in positive mode.

## 3.1 Power generator and control unit

Power generator and control unit - The power supply control the amount of energy consumed. First, it has a time control function which controls the length of time that current flows during each pulse; this is called "on time." Then it is control the amount of current allowed to flow during each pulse. These pulses are of very short duration and are measured in microseconds. There is a handy rule of thumb to determine the amount of current a particular size of electrode should use: for an efficient removal rate, each square inch of electrode calls for 50 A. Low current level for large electrode will extend overall machine time unnecessarily. Conversely, too heavy a current load can damage the work piece of electrode.

## 3.2 Mechanism of Tool wears

Tool wear is an important factor because if affects dimensional accuracy and the shape produced. Tool wear is related to the melting point of the materials. Tool wear is affected by the precipitation of carbon from the hydrocarbon dielectric on the electrode surface during sparking. Also the rapid wear on the electrode edge was because of the failure of carbon to precipitate at difficult to reach regions of the electrode. TWR is expressed as the ratio of the difference of weight of the tool before and after machining to the machining time. Table 1 shows experiment runs

according to Design of Experiments. The corresponding output of SR, MRR and TWR can be recorded for each experiment.

## 3.3 Effect of Material Removal Rate:

For any kind of machining process Material Removal Rate is considered tobe important machining characteristics, EDM is an electro thermal process, the material removal takes place by melting and evaporation. The fig 1. Plot between MRR (g/cm3) Vs Current, Pulse On, and Pulse Off. Taguchi's analysis is used to interpret the relation between MRR and all input parameters. From the Fig.1. it is evident that MRR is optimum when Current reaches 15A, after the MRR value decreased. The 40µs, the MRR is increased linearly in Pulse ON time. The MRR shows directly proportional to Pulse OFF time upto 6µs, after the MRR value dropped.

## 3.4 Effect of Surface Roughness:

The fig.2.is plot between SR ( $\mu$ m) Vs Current, Pulse On, Pulse Off. The influence of individual input parameters can be analyzed using Taguchi's method. Here SR is Optimum for 10A current, further SR value increases when current increases. The Pulse On time increases, value of SR also decreases upto 10 $\mu$ s after that SR increases further increase increasing of Pulse On time. The SR value in contradict with Pulse On time. Here Pulse Off time increases, then the SR value is increased and shows the optimum SR value at attained at 2  $\mu$ s.

## 3.5 Effect of Tool Wear Rate:

The Effect of TWR vs Current, Pulse On and Pulse Off time shows in fig.3. The graph is plotted and interactions can be evaluated using Taguchi's Method. Tool wear is optimum at peak current of 5 A. From the graph, when current value Increases, the tool wear gradually increases and both parameters are inversely proportional to each other. Further Pulse On time increases, tool wear rate also increases significantly. Hence minimum Pulse On time must be given to increase the Tool life. Pulse Off time also influences same like pulse on time for Tool wear rate. The Tool wear optimum at Pulse off time 2 µs, further increases the pulse off time, Tool wear also increased slightly.

## 4. Result and Discussion:

**Table.1.L16 Experimental Results** 

Experiment No	Current (Amps)	Pulse ON	Pulse Off	SR	MRR	TWR
	( <b>-</b> F)	(µs)	(µs)	(µm)	(g/cm <sup>3</sup> )	(g/cm <sup>3</sup> )
1.	5	10	2	4.927	0.052	0.0002
2.	5	20	4	6.832	0.0905	0.0005
3.	5	30	6	8.421	0.115	0.0006
4.	5	40	8	7.329	0.2464	0.0022
5.	10	10	4	5.394	0.124	0.0046
6.	10	20	2	6.921	0.204	0.0004
7.	10	30	8	7.028	0.252	0.0008
8.	10	40	6	6.032	0.3598	0.3598
9.	15	10	6	4.868	0.4184	0.0024
10.	15	20	8	7.962	0.2532	0.0202
11.	15	30	2	6.702	0.3762	0.023
12.	15	40	4	7.568	0.1636	0.0186
13.	20	10	8	7.108	0.1646	0.0322
14.	20	20	6	7.838	0.3794	0.0334
15.	20	30	4	6.913	0.3348	0.0164
16.	20	40	2	8.172	0.2594	0.0198

## **3.5 Regression Equation:**

The regression equation is for MRR, SR & TWR predicted from the minitab software shown in equation 1 2 & 3.

 $\begin{aligned} & \textbf{MRR} \ (\textbf{g/cm3}) = 0.2371 - 0.1111 \ \text{Current\_5} - 0.0021 \ \text{Current\_10} + 0.0658 \ \text{Current\_15} + 0.0475 \ \text{Current\_20} \\ & - 0.0473 \ \text{Pulse On\_10} - 0.0053 \ \text{Pulse On\_20} + 0.0324 \ \text{Pulse On\_30} + 0.0202 \ \text{Pulse On\_40} - \\ & - 0.0142 \ \text{Pulse Off\_2} - 0.0589 \ \text{Pulse Off\_4} + 0.0811 \ \text{Pulse Off\_6} - 0.0080 \ \text{Pulse Off\_8} \end{aligned}$ 

**SR** ( $\mu$ m) = 6.876 + 0.001 Current\_5 - 0.532 Current\_10 - 0.101 Current\_15 + 0.632 Current\_20-1.302 Pulse On\_10 + 0.512 Pulse On\_20 + 0.390 Pulse On\_30 + 0.399 Pulse On\_40- 0.195 Pulse Off\_2 - 0.199 Pulse Off\_4 - 0.086 Pulse Off\_6 + 0.481 Pulse Off\_8 (2)

 $\begin{array}{l} \textbf{TWR} \ ((\textbf{g/cm3})) = 0.0334 - 0.0326 \ \text{Current\_5} + 0.0580 \ \text{Current\_10} - 0.0174 \ \text{Current\_15} - 0.0080 \ \text{Current\_20} \\ - 0.0236 \ \text{Pulse On\_10} - 0.0198 \ \text{Pulse On\_20} - 0.0232 \ \text{Pulse On\_30} + 0.0667 \ \text{Pulse On\_40} - \\ 0.0226 \ \text{Pulse Off\_2} - 0.0234 \ \text{Pulse Off\_4} + 0.0656 \ \text{Pulse Off\_6} - 0.0196 \ \text{Pulse Off\_8} \end{array}$ 

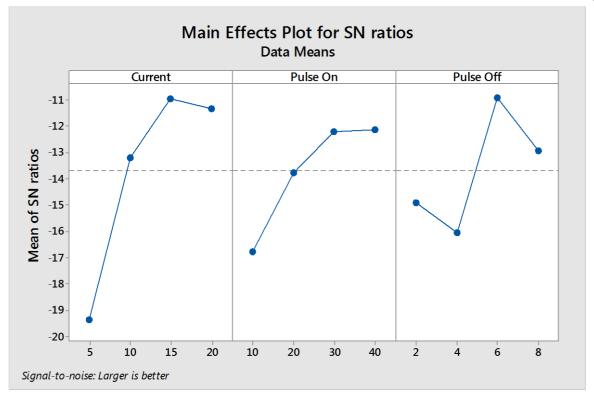


Fig: 1.MRR Vs Current, Pulse On, Pulse Off.

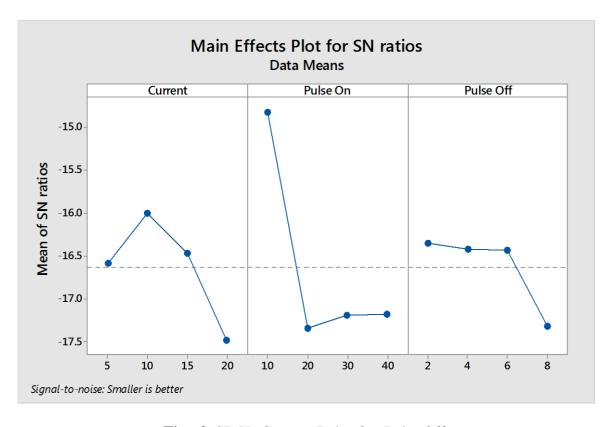


Fig: 2. SR Vs Current, Pulse On, Pulse Off.

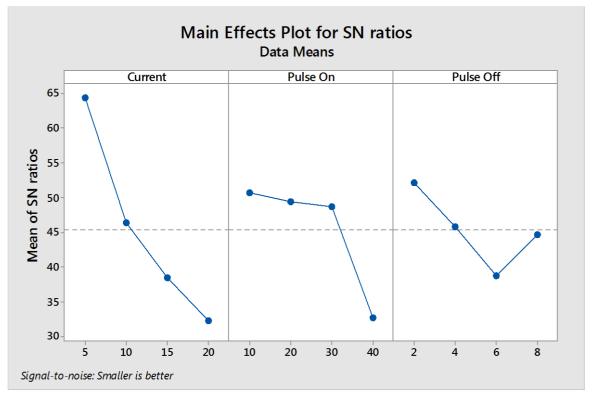


Fig: 3 TWR vs Current, Pulse On and Pulse Off time

## 4. Conclusion

From the experiments done, the following conclusion can be drawn. Aluminium Multiwall Carbon Nanotubes can be fabricated by Stir casting technique. Further the machining is done by EDM with copper is used as a tool. There are three input parameters with Four level of factors can be taken to conduct 16 experiments and output parameters like TWR, MRR and SR values can be noted. Effect of Each parameter on TWR, SR and MRR can be plotted. From these graphs, MRR shows optimum at 15A current, 40 µs pulse On and 06 µs Pulse off value. Similarly, SR value is optimum for 10A current, 10 µs Pulse On and 02 µs Pulse Off value. TWR shows good response when current value reaches 05 A, 10 us Pulse On and 02 µs Pulse Off value. The mathematical model also presented to predict the optimized process parameter to achieve high MRR and low SR and TWR.

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